

問1

$$(1) A \cdot B = -1 + 4 + 9 = 12$$

$$(2) A \times B = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & 3 \\ -1 & 2 & 3 \end{vmatrix} = \begin{vmatrix} 2 & 3 \\ 2 & 3 \end{vmatrix} \hat{i} + \begin{vmatrix} 3 & 1 \\ 3 & -1 \end{vmatrix} \hat{j} + \begin{vmatrix} 1 & 2 \\ -1 & 2 \end{vmatrix} \hat{k}$$

$$= (6-6)\hat{i} + (-3-3)\hat{j} + (2-2)\hat{k}$$

$$= -6\hat{j} + 4\hat{k}$$

$$\therefore A \times B = (0, -6, 4)$$

$$(3) e_A = \frac{A}{|A|} = \frac{1}{\sqrt{14}} A = \left(\frac{1}{\sqrt{14}}, \frac{2}{\sqrt{14}}, \frac{3}{\sqrt{14}} \right)$$

$$e_B = \left(-\frac{1}{\sqrt{14}}, \frac{2}{\sqrt{14}}, \frac{3}{\sqrt{14}} \right)$$

$$(4) A \times e_B \text{ は } A \perp A \times e_B, \quad B \perp A \times e_B$$

よって、 A と B のなす角を θ とする。

$$|A \times e_B| = |A| \sin \theta$$

$$e_B \times (A \times e_B) \text{ は } B \perp e_B \times (A \times e_B), \quad A \times e_B \perp e_B \times (A \times e_B)$$

なので、 $e_B \times (A \times e_B)$ は A, B を含む平面上で B と垂直なベクトルである。

$$|e_B \times (A \times e_B)| = A \sin \theta \cdot \sin 90^\circ = A \sin \theta$$

A を B に垂直なベクトルに分解したとき $\pm$ は $A \sin \theta$ なので、

$e_B \times (A \times e_B)$ は求める B に垂直なベクトルである。

また、 $A \cdot e_B = A \cos \theta$ で求める B に平行なベクトルの大きさは $A \cos \theta$ なので、

$$A = (A - e_B) e_B + e_B \times (A \times e_B)$$

1b) 2.

$$(1) a = a_0 + a_1 t$$

$$v = \int_1^{-1} a dt = \int_1^{-1} (a_0 + a_1 t) dt$$

$$= a_0 t + \frac{1}{2} a_1 t^2 + C \quad (C: \text{積分定数})$$

$$t=0 \text{ のとき } v(0) = v_0 \quad \therefore v_0 = C$$

$$\therefore v = a_0 t + \frac{1}{2} a_1 t^2 + v_0$$

$$x = \int (a_0 t + \frac{1}{2} a_1 t^2 + v_0) dt$$

$$= \frac{1}{2} a_0 t^2 + \frac{1}{6} a_1 t^3 + v_0 t + C' \quad (C': \text{定数})$$

$$t=0 \text{ のとき } x(0) = x_0 \quad \therefore x_0 = C'$$

$$x = \frac{1}{2} a_0 t^2 + \frac{1}{6} a_1 t^3 + v_0 t + x_0$$

$$(2) x = A e^{-Bt} \cos \omega t$$

$$v = \dot{x} = -A B e^{-Bt} \cos \omega t - A \omega e^{-Bt} \sin \omega t$$

$$\begin{aligned} a = \dot{v} &= A B^2 e^{-Bt} \cos \omega t + A B \omega \sin \omega t + A B \omega e^{-Bt} \sin \omega t - A \omega^2 e^{-Bt} \cos \omega t \\ &= A B^2 e^{-Bt} \cos \omega t + 2 A B \omega \sin \omega t - A \omega^2 e^{-Bt} \cos \omega t \\ &= A e^{-Bt} (-B^2 \cos \omega t + 2 B \omega \sin \omega t - \omega^2 \cos \omega t) \end{aligned}$$

$$(3) a = p \frac{g}{r+x}$$

$$\frac{d^2 x}{dt^2} = p \frac{g}{r+x}$$

$x(t) = 0$ である微分方程式

$$\frac{d^2 x}{dt^2} = f(x) \quad (f(x) = p \frac{g}{r+x})$$

$$\frac{d^2 x}{dt^2} \cdot \frac{dx}{dt} = f(x) \cdot \frac{dx}{dt}$$

両辺 x について積分する。

$$\int \frac{d^2 x}{dt^2} \cdot \frac{dx}{dt} \cdot dt = \int f(x) \cdot dx$$

$$\frac{1}{2} \left(\frac{dx}{dt} \right)^2 = \int p \frac{g}{r+x} dx$$

$$\therefore \frac{1}{2} \left(\frac{dx}{dt} \right)^2 = v^2 \text{ である。 } \frac{1}{2} v^2 = p g \ln |r+x| + C$$

$$x(0) = 0, v(0) = 0, a(0) = \frac{p g}{r} > 0, x > 0, v > 0, a > 0, p g \ln |r| + C = 0$$

$$\therefore C = -p g \ln |r|$$

$$\frac{1}{2}v^2 = \cancel{p\theta} \ln|r+x| - \cancel{p\theta} \ln|r|$$

$$\ln|r+x| = \frac{v^2}{2p\theta} + \ln r$$

$$r+x = e^{\frac{v^2}{2p\theta} + \ln r}$$

$$x = re^{\frac{v^2}{2p\theta}} - r$$

$$a = \frac{p\theta}{r + re^{\frac{v^2}{2p\theta}} - r} = \frac{p\theta}{re^{\frac{v^2}{2p\theta}}}$$

由3.

(1) x, y, z 方向の速度, 加速度を $v_x, v_y, v_z, a_x, a_y, a_z$ とし,

$$x \text{ 方向: } ma_x = -mr(v_x - \cancel{V_x})$$

$$y \text{ 方向: } ma_y = -mr(v_y - \cancel{V_y})$$

$$z \text{ 方向: } ma_z = -mg$$

(2) z 方向について $a_z = -g$

$$v_z(t) = \int a_z dt = -gt + C \quad (C: \text{定数})$$

$$v_z(0) = B = C \text{ より } v_z(t) = -gt + B$$

$$x_z(t) = \int v_z(t) dt = -\frac{1}{2}gt^2 + Bt + C' \quad (C': \text{定数})$$

$$x_z(0) = 0 = C' \text{ より } x_z(t) = -\frac{1}{2}gt^2 + Bt$$

x 方向について,

$$\frac{dv_x(t)}{dt} = -r(v_x(t) - \cancel{V_x})$$

$$\frac{1}{v_x(t) - \cancel{V_x}} \cdot \frac{dv_x(t)}{dt} = -r$$

両辺 t で積分すると,

$$\int \frac{dv_x(t)}{v_x(t) - \cancel{V_x}} = -\int r dt$$

$$\ln|v_x(t) - \cancel{V_x}| = -rt + C \quad (C: \text{定数})$$

$$\therefore v_x(t) = \cancel{V_x} + e^{-rt+C}$$

$$= \cancel{V_x} + D e^{-rt} \quad (D = \pm e^C)$$

$$v_x(0) = A = \cancel{V_x} + D \quad \therefore D = A - \cancel{V_x}$$

$$\therefore v_x(t) = \cancel{V_x} + (A - \cancel{V_x}) e^{-rt}$$

$$x(t) = \int v_x(t) dt = \cancel{V_x} t - \frac{1}{r}(A - \cancel{V_x}) e^{-rt} + C \quad (C: \text{定数})$$

$$x(0) = -\frac{1}{r}(A - \cancel{V_x}) + C = 0 \quad C = \frac{1}{r}(A - \cancel{V_x})$$

$$x(t) = \cancel{V_x} t - \frac{1}{r}(A - \cancel{V_x}) e^{-rt} + \frac{1}{r}(A - \cancel{V_x})$$

$$= \cancel{V_x} t + \frac{1}{r}(A - \cancel{V_x})(1 - e^{-rt})$$

同様に $v_z(t) = V_z + D'e^{-rt}$ (D' : 定数)

$$v_z(0) = 0 = V_z + D'$$

$$\therefore D' = -V_z$$

$$v_z(t) = V_z - V_z e^{-rt}$$

$$y(t) = \int v_z(t) dt$$

$$= V_z t + \frac{1}{r} V_z e^{-rt} + C' \quad (C': \text{定数})$$

$$y(0) = \frac{1}{r} V_z + C' = 0$$

$$C' = -\frac{1}{r} V_z$$

$$y(t) = V_z t + \frac{1}{r} V_z e^{-rt} - \frac{1}{r} V_z$$

$$= V_z t + \frac{1}{r} V_z (e^{-rt} - 1)$$

(3) 着地までにかかる時間を T ($T > 0$) とする。

$$z(T) = 0 \text{ より}$$

$$-\frac{1}{2} g T^2 + B T = 0$$

$$-T \left(\frac{gT}{2} - B \right) = 0$$

$$\therefore T = \frac{2B}{g}$$

$$x(T) = 0 \text{ より}$$

$$0 = V_x T - \frac{1}{r} A e^{-rT} + \frac{1}{r} V_x e^{-rT} + \frac{1}{r} A - \frac{1}{r} V_x$$

$$(rT + e^{-rT} - 1) V_x = A e^{-rT} - A = -A(1 - e^{-rT})$$

$$T = \frac{2B}{g}$$

$$\left(\frac{2rB}{g} + e^{-\frac{2rB}{g}} - 1 \right) V_x = -A(1 - e^{-\frac{2rB}{g}})$$

$$(2rB + g e^{-\frac{2rB}{g}} - g) V_x = -A g (1 - e^{-\frac{2rB}{g}})$$

$$V_x = - \frac{A g (1 - e^{-\frac{2rB}{g}})}{2rB + g e^{-\frac{2rB}{g}} - g}$$

例4

$$\begin{cases} x = \sinh h \\ y = 1 - \cosh h \\ z = h \end{cases}$$

$$\begin{aligned} (1) \quad g(h) &= \int_0^h \sqrt{\left(\frac{dx}{dh}\right)^2 + \left(\frac{dy}{dh}\right)^2 + \left(\frac{dz}{dh}\right)^2} dh \\ &= \int_0^h \sqrt{\cosh^2 h + \sinh^2 h + 1} dh \\ &= \int_0^h \sqrt{2} dh = \sqrt{2} h \end{aligned}$$

$$(2) \quad \frac{dx}{dt} = \cosh h \quad \frac{dy}{dt} = \sinh h \quad \frac{dz}{dt} = 1$$

$$\begin{aligned} \vec{x}(h) &= \frac{1}{\sqrt{\cosh^2 h + \sinh^2 h + 1}} (\cosh h, \sinh h, 1) \\ &= \left(\frac{\cosh h}{\sqrt{2}}, \frac{\sinh h}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right) \end{aligned}$$

$$(3) \quad ds = \sqrt{2} dh$$

$$\rho(h) = \frac{1}{\left| \frac{d\vec{x}}{dh} \right|} = \frac{\sqrt{2}}{\left| \frac{d\vec{x}}{dh} \right|}$$

$$\frac{d\vec{x}}{dh} = \left(-\frac{\sinh h}{\sqrt{2}}, \frac{\cosh h}{\sqrt{2}}, 0 \right)$$

$$\begin{aligned} \left| \frac{d\vec{x}}{dh} \right| &= \left(\frac{\sinh h}{\sqrt{2}} \right)^2 + \left(\frac{\cosh h}{\sqrt{2}} \right)^2 \\ &= \frac{1}{2} \end{aligned}$$

$$\rho(h) = \frac{\sqrt{2}}{\frac{1}{2}} = 2\sqrt{2}$$

$$m \frac{d^2 \vec{z}(t)}{dt^2} = -mg$$

$$\frac{d^2 \vec{z}(t)}{dt^2} = -g$$

$$\vec{z}(t) = \frac{d\vec{z}(t)}{dt} = -gt + C \quad (C: \text{常数})$$

$$Z(0) = 0 \quad H(h) = \left(\frac{\cosh h}{\sqrt{2}}, \frac{i \sinh h}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right) \neq \gamma$$

$$v_z(0) = \frac{1}{\sqrt{2}} v_0$$

$$\therefore C = \frac{1}{\sqrt{2}} v_0$$

$$\begin{aligned} Z(t) &= \int v_z(t) dt = \int \left(-gt + \frac{1}{\sqrt{2}} v_0 \right) dt \\ &= -\frac{1}{2} g t^2 + \frac{1}{\sqrt{2}} v_0 t + C' \quad (C': \text{定数}) \end{aligned}$$

$$Z(0) = 0 = C'$$

$$Z(t) = -\frac{1}{2} g t^2 + \frac{1}{\sqrt{2}} v_0 t$$