

$$\therefore \Delta U - \Delta T = \left(1 - \frac{m_1 + m_2}{m_1 + m_2 + \frac{I}{r^2}}\right) (m_1 - m_2) g h$$

$$= \frac{m_1 - m_2}{m_1 + m_2 + \frac{I}{r^2}} g h \frac{I}{r^2} \quad \uparrow \quad \ddot{z}_1 h \frac{I}{r^2} \quad (2)$$

$$\dot{z}_1^2 = 2 \ddot{z}_1 h \quad \uparrow \quad \ddot{z}_1 h = \frac{1}{2} \dot{z}_1^2 \quad \uparrow \quad = \frac{1}{2} r^2 \dot{\varphi}^2$$

$$\dot{z}_1 = r \dot{\varphi}$$

$$\therefore \Delta U - \Delta T = \frac{1}{2} I \dot{\varphi}^2 \quad // \quad (5)$$

問2. (1) $T = \frac{m}{2} (v_r^2 + v_\theta^2) = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\theta}^2) \quad // \quad (10)$

$$(2) \quad \frac{dW}{dt} = m (a_r v_r + a_\theta v_\theta) = m \{ \dot{r} (\ddot{r} - r \dot{\theta}^2) + r \dot{\theta} (2 \dot{r} \dot{\theta} + \ddot{\theta}) \}$$

$$= m (\dot{r} \ddot{r} + r \dot{\theta}^2 + r^2 \dot{\theta} \ddot{\theta})$$

$$-\frac{1}{2} (1) \text{に} \quad \frac{dT}{dt} = m (\dot{r} \ddot{r} + r \dot{\theta}^2 + r^2 \dot{\theta} \ddot{\theta}) \quad \text{と} \text{も} \text{同} \text{じ}$$

$$\therefore \frac{dW}{dt} = \frac{dT}{dt} \quad // \quad (10)$$

(3) F は中心力 $F_\theta = 0$

$$\therefore \frac{dW}{dt} = F_r v_r = - \frac{G m M}{r^2} \dot{r} = \frac{d}{dt} \left(\frac{G m M}{r} \right) = - \frac{dU}{dt}$$

(2) と 左辺は $\frac{dT}{dt}$ と等しいから

$$\frac{dT}{dt} + \frac{dU}{dt} = \frac{d}{dt} (T + U) = 0 \quad \therefore E = T + U \text{ は一定} \quad //$$

(5)